# ITS Overseas single-lane speed radar

### RD106@A-1-OS



#### Features

- Support two-way trigger, retrograde capture
- Support formal and side loading;
- Adopt 24GHz MMIC technology, superior performance;
- High gain and low sidelobe microstrip antenna design technology can effectively avoid adjacent channel target interference.;
- Accurate ranging and velocity measurement for single targets, accurate positioning;
- High-precision fixed-point capture, the position error is within 1 m, and the capture rate is above 99%.;
- Strong environmental adaptability, and the detection performance is not disturbed by external environment such as light, dust, rain and snow.

#### **Specifications**

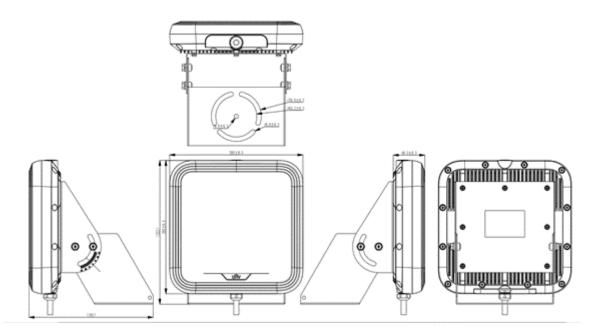
Model	RD106@A-1-OS	
Performance		
Number of lanes	1	
Vehicle capture rate	≥99%	
Speed measurement error	≥100km/h (-1-0)km/h <100km/h(-0.5-0)km/h	
Trigger Consistency	≤±0.5m	

# UNV

# DATASHEET

Speed measurement range	10 km/h ~250km/h	
Tracking distance	18~38m	
Mounting height	4~8m	
Lane width	2.75~5m adjustable	
Interface Characteristics		
Power supply	RS485	
Communication interface	DC9~12V 0.3A	
General Features		
Weight	0.45kg	
Antenna beam 3dB width	6°×6°	
Working center frequency	24.15GHz±45MHz	
Power waste	≤2W	
Operation temperature	-40°C~70°C	
Working humidity	0-95%RH	
Protection grade	IP66	
Dimensions (L×W×H)	205X221X191mm	

## Dimensions



# UNV

### **Ordering Info**

Product Model	Config	Description
RD106	A-1-OS	ITS Multi-target tracking and speed measurement radar(Single lane), With bracket, Can be powered by the camera 12V

#### Zhejiang Uniview Technologies Co., Ltd.

No. 369, Xietong Road, Xixing Sub-district, Binjiang District, Hangzhou City, 310051, Zhejiang Province, China

Email: overseasbusiness@uniview.com; globalsupport@uniview.com

http://www.uniview.com

 $\ensuremath{\mathbb{C}}$  2024-2025 Zhejiang Uniview Technologies Co., Ltd. All rights reserved.

\*Product specifications and availability are subject to change without notice.

\*Despite our best efforts, technical or typographical errors may exist in this document. Uniview cannot be held responsible for any such

errors and reserves the right to change the contents of this document without prior notice.